

The ADM canonical formalism for gravitating spinning objects

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Outline

- 1 Introduction
 - Spinning objects in SR and GR
 - The ADM formalism
- 2 Our Formulation
 - Strategy of our approach
 - Details on the derivation
 - Gauge independent formalism?
- 3 Application
 - Hamiltonians
 - Comparison with other Methods

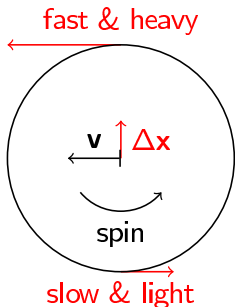


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Frame-Dependence of Center and Spin in SR



- Spinning object moving with velocity \mathbf{v} .
- Shall have constant density in rest frame.
- Upper hemisphere faster than lower.
- Upper hemisphere more massive than lower.
- Center of mass displaced by $\Delta \mathbf{x}$.
- Spin depends on location of center.

- Description by means of a 4-tensor $S^{\mu\nu}$:
 - Spin is $S^{ij} = \epsilon^{ijk} S_k$.
 - Mass dipole related to S^{0i} .
- Spin supplementary condition (SSC) fixates S^{0i} in terms of S^{ij} .



SSC in SR

- Usefull SSCs are, with mass m and 4-momentum p_μ :
 - Møller SSC: $\tilde{S}^{0\mu} = 0$
 - Fokker-Synge-Pryce (covariant) SSC: $S^{\mu\nu} p_\nu = 0$
 - Newton-Wigner (canonical) SSC: $m\hat{S}^{0\mu} - \hat{S}^{\mu\nu} p_\nu = 0$
- Canonical structure depends on SSC, and can be complicated.
- In covariant SSC, with position \mathbf{z} :

$$\{z^i(t), z^j(t)\} = \frac{S^{ij}}{m^2} - \frac{p^i S^{0j} - p^j S^{0i}}{m^2 p^0}, \quad \dots$$

- In Newton-Wigner SSC:

$$\{\hat{z}^i(t), p_j(t)\} = \delta_{ij}, \quad \{\hat{S}_i(t), \hat{S}_j(t)\} = \epsilon_{ijk} \hat{S}_k(t)$$

$$\{\hat{\mathbf{S}}^2, \dots\} = 0 \quad \Rightarrow \quad \hat{\mathbf{S}}^2 = \text{const.}$$



Spin in GR

- We restrict to linear order in spin here:
 - No deformation by spin included.
 - Linear order is **universal**.
- Stress-Energy Tensor in covariant SSC:

$$\begin{aligned}
 \sqrt{-g} T^{\mu\nu} &= \int d\tau \left[m u^\mu u^\nu \delta_{(4)} - (S^{\alpha(\mu} u^{\nu)}) \delta_{(4); \alpha} \right] \\
 &= p^\mu v^\nu \delta - (S^{\alpha(\mu} v^{\nu)})_{, \alpha} \delta - S^{\alpha(\mu} \Gamma_{\alpha\beta}^{\nu)} v^\beta \delta \\
 \delta_{(4)} &\equiv \delta(x - z), \quad \delta \equiv \delta(\mathbf{x} - \mathbf{z})
 \end{aligned}$$

- EOM follow from $T^{\mu\nu}_{; \nu} = 0$:

$$\frac{DS^{\mu\nu}}{d\tau} = 0, \quad \frac{Dp_\mu}{d\tau} = \frac{1}{2} S^{\lambda\nu} u^\gamma R_{\mu\gamma\nu\lambda}$$

- Actions are known for covariant SSC in external grav. fields.



Some Literature on Spin in Relativity



G. N. Fleming

Covariant Position Operators, Spin, and Locality

Phys. Rev. **137**, B 188 (1965)



A. J. Hanson and T. Regge

The Relativistic Spherical Top

Ann. Phys. (N.Y.) **87**, 498 (1974)



A. Trautman

Lectures on General Relativity

Gen. Rel. Grav. **34**, 721 (2002)



J. Natário

Tangent Euler Top in General Relativity

arXiv:gr-qc/0703081v1



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Preliminaries

- 3 + 1 decomposition:

$$g_{\mu\nu} = \begin{pmatrix} N^i N_j - N^2 & N_j \\ N_j & \gamma_{ij} \end{pmatrix}, \quad N^2 g^{\mu\nu} = \begin{pmatrix} -1 & N^i \\ N^j & N^2 \gamma^{ij} - N^i N^j \end{pmatrix}$$

$$K_{ij} = -N \Gamma_{ij}^0, \quad n_\mu = (-N, 0, 0, 0)$$

- Canonical Variables:

$$\{\gamma_{ij}(\mathbf{x}, t), \pi^{kl}(\mathbf{x}', t)\} = 16\pi \delta_{ij}^{kl} \delta(\mathbf{x} - \mathbf{x}')$$

- In the following, we will **always** restrict to:

$$\pi^{ij} = -\sqrt{\gamma}(\gamma^{ik}\gamma^{jl} - \gamma^{ij}\gamma^{kl})K_{kl}$$



Hamiltonian before Gauge Fixing

$$H = \int d^3\mathbf{x} (N\mathcal{H} - N^i\mathcal{H}_i) + E[\gamma_{ij}]$$

$$\mathcal{H} = \mathcal{H}^{\text{field}} + \mathcal{H}^{\text{matter}}$$

$$\mathcal{H}_i = \mathcal{H}_i^{\text{field}} + \mathcal{H}_i^{\text{matter}}$$

$$\mathcal{H}^{\text{field}} = -\frac{1}{16\pi\sqrt{\gamma}} \left[\gamma R + \frac{1}{2} (\gamma_{ij}\pi^{ij})^2 - \gamma_{ij}\gamma_{kl}\pi^{ik}\pi^{jl} \right]$$

$$\mathcal{H}_i^{\text{field}} = \frac{1}{8\pi} \gamma_{ij}\pi^{jk}_{;k}$$

- Lapse N and shift N^i are Lagrange multipliers.
- Surface term $E[\gamma_{ij}]$ reflects boundary conditions.
- 3-dim. geometry of $t = \text{const.}$ surfaces important.



Field Equations before Gauge Fixing

$$H = \int d^3\mathbf{x}(N\mathcal{H} - N^i\mathcal{H}_i) + E[\gamma_{ij}]$$

- 12 evolution equations:

$$\frac{1}{16\pi} \frac{\partial \pi^{ij}}{\partial t} = - \frac{\delta H}{\delta \gamma_{ij}}, \quad \frac{1}{16\pi} \frac{\partial \gamma_{ij}}{\partial t} = \frac{\delta H}{\delta \pi^{ij}}$$

- Four constraint equations:

$$\frac{\delta H}{\delta N} \equiv \mathcal{H} = 0, \quad - \frac{\delta H}{\delta N^i} \equiv \mathcal{H}_i = 0$$

- Compare with 3 + 1 version of the Einstein equations:

$$\mathcal{H}^{\text{matter}} = \sqrt{\gamma} T^{\mu\nu} n_{\mu} n_{\nu}, \quad \mathcal{H}_i^{\text{matter}} = -\sqrt{\gamma} T_i^{\nu} n_{\nu}$$

- Matter parts can be **calculated** using the stress-energy tensor, cf. Boulware and Deser (1967).



The ADMTT Gauge

- ADMTT gauge is defined by:

$$0 = 3\gamma_{ij,j} - \gamma_{jj,i}$$

$$0 = \pi^{ii}$$

- Equivalent to a decomposition:

$$\gamma_{ij} = \left(1 + \frac{1}{8}\phi\right)^4 \delta_{ij} + h_{ij}^{\text{TT}}$$

$$\pi^{ij} = \tilde{\pi}^{ij} + \pi_{\text{TT}}^{ij}$$

- Also fixates Lapse and Shift:

$$(3\gamma_{ij,j} - \gamma_{jj,i})_{,0} = 0 \quad \Rightarrow \quad 3\Delta N_i + N_{j,ji} = \dots$$

$$\pi^{ii}_{,0} = 0 \quad \Rightarrow \quad \Delta N = \dots$$



The Reduced Hamiltonian

- Constraints together with gauge conditions allow reduction of phase space.
- Reduction in ADMTT gauge:

$$\gamma_{ij} = \left(1 + \frac{1}{8}\phi\right)^4 \delta_{ij} + h_{ij}^{\text{TT}}$$

$$\pi^{ij} = \tilde{\pi}^{ij} + \pi_{\text{TT}}^{ij}$$

- Constraints are solved for ϕ and $\tilde{\pi}^{ij}$.
- Remaining canonical field variables:

$$\{h_{ij}^{\text{TT}}(\mathbf{x}, t), \pi_{\text{TT}}^{kl}(\mathbf{x}', t)\} = 16\pi\delta_{ij}^{\text{TT}kl}\delta(\mathbf{x} - \mathbf{x}')$$

- **Surface expression E turns into reduced Hamiltonian H_{ADM} .**
- For general gauges, Dirac-brackets must be used.



Global Poincaré Invariance I

- Global Poincaré group is a consequence of asymptotic flatness.
- Generators P^μ and $J^{\mu\nu}$ are conserved.
- Poincaré algebra:

$$\{P^\mu, P^\nu\} = 0$$




$$\{P^\mu, J^{\rho\sigma}\} = -\eta^{\mu\rho} P^\sigma + \eta^{\mu\sigma} P^\rho$$

$$\{J^{\mu\nu}, P^{\rho\sigma}\} = -\eta^{\nu\rho} J^{\mu\sigma} + \eta^{\mu\rho} J^{\nu\sigma} + \eta^{\sigma\mu} J^{\rho\nu} - \eta^{\sigma\nu} J^{\rho\mu}$$

- 3 + 1 decomposition:
 - Energy: $E \equiv P^0$
 - Momentum: P^i
 - Angular momentum: $J^i \equiv \frac{1}{2}\epsilon^{ijk} J_{jk}$
 - Boost: $J^{i0} \equiv K^i \equiv G^i - t P^i$
 - Center of mass: $X^i \equiv G^i/E$



Some Literature on the ADM Formalism

-  R. Arnowitt, S. Deser, and C. W. Misner
The Dynamics of General Relativity
in *Gravitation: An Introduction to Current Research*, edited by
L. Witten (Wiley, New York, 1962); arXiv:gr-qc/0405109
-  A. Hanson, T. Regge, and C. Teitelboim
Constrained Hamiltonian Systems
Accademia Nazionale dei Lincei, Roma, 1976
-  P. Jaranowski and G. Schäfer
*Third post-Newtonian higher order ADM Hamiltonian
dynamics for two-body point-mass systems*
Phys. Rev. D **57**, 7274 (1998)



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Conditions on the Matter Hamiltonian

$$H^{\text{matter}} = \int d^3\mathbf{x} (N\mathcal{H}^{\text{matter}} - N^i\mathcal{H}_i^{\text{matter}})$$

- $\mathcal{H}^{\text{matter}}$ and $\mathcal{H}_i^{\text{matter}}$ must be independent of N and N^i .
- Constraints coincide with the Einstein equations iff:

$$\mathcal{H}^{\text{matter}} = \sqrt{\gamma} T^{\mu\nu} n_\mu n_\nu, \quad \mathcal{H}_i^{\text{matter}} = -\sqrt{\gamma} T_i^\nu n_\nu$$

- Evolution equations coincide with the Einstein equations iff:

$$\frac{\delta H^{\text{matter}}}{\delta \pi^{ij}} = 0, \quad \frac{\delta H^{\text{matter}}}{\delta \gamma^{ij}} = \frac{1}{2} N \sqrt{\gamma} T_{ij}$$

- $\mathcal{H}^{\text{matter}}$ and $\mathcal{H}_i^{\text{matter}}$ must be independent of N, N^i and π^{ij} .
- Construct them as **3-dim. covariant generalisations** of their Minkowski versions.



Our Strategy

- Calculate matter parts using stress-energy tensor in Minkowski space in covariant SSC:

$$\mathcal{H}^{\text{matter}} = \sqrt{\gamma} T^{\mu\nu} n_\mu n_\nu, \quad \mathcal{H}_i^{\text{matter}} = -\sqrt{\gamma} T_i^\nu n_\nu$$

- Go over to Newton-Wigner SSC.
- Take 3-dim. covariant generalisations of $\mathcal{H}^{\text{matter}}$ and $\mathcal{H}_i^{\text{matter}}$.
- Redefine momentum, such that $P_i = \int d^3\mathbf{x} \mathcal{H}_i^{\text{matter}}$.
- Redefine spin, such that $\mathbf{S}^2 = \text{const.}$
- Questions that must be answered:
 - Is the calculation with the 4-dim. covariant stress-energy tensor possible?
 - Is $\frac{\delta H^{\text{matter}}}{\delta \gamma^{ij}} = \frac{1}{2} N \sqrt{\gamma} T_{ij}$ fulfilled?
 - Is the Poincaré algebra fulfilled?



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Minkowski Space Versions

- Stress-Energy tensor in covariant SSC:

$$T^{\mu\nu} = p^\mu v^\nu \delta - (S^{\alpha(\mu} v^{\nu)})_{,\alpha}$$

- Use Newton-Wigner variables, $np \equiv n_\mu p^\mu = -\sqrt{m^2 + \gamma^{ij} p_i p_j}$:

$$\hat{z}^\mu = z^\mu - \frac{S^{\mu\nu} n_\nu}{m - np}$$

$$S^{\mu\nu} = \hat{S}^{\mu\nu} + p^\mu n_\lambda \hat{S}^{\nu\lambda} / m - p^\nu n_\lambda \hat{S}^{\mu\lambda} / m$$

- Result:

$$\sqrt{\gamma} \hat{T}^{\mu\nu} n_\mu n_\nu = -np\delta - \left[\delta_{ij} \delta_{kl} \frac{p_l}{m - np} \hat{S}_{jk} \delta \right]_{,i}$$

$$-\sqrt{\gamma} \hat{T}_i^\nu n_\nu = p_i \delta + \frac{1}{2} \left[\delta_{mk} \hat{S}_{ik} \delta \right]_{,m}$$

$$- \left[(\delta_{mk} \delta_{ip} + \delta_{mp} \delta_{ik}) \delta_{ql} \hat{S}_{qp} \frac{p_l p_k}{np(m - np)} \delta \right]_{,m}$$



Redefinition of Momentum

- 3-dim. covariant generalisation:

$$\mathcal{H}^{\text{matter}} = -np\delta - \left[\gamma^{ij} \gamma^{kl} \frac{p_l}{m - np} \hat{S}_{jk} \delta \right]_{,i}$$

$$\begin{aligned} \mathcal{H}_i^{\text{matter}} &= p_i \delta + \frac{1}{2} \left[\gamma^{mk} \hat{S}_{ik} \delta \right]_{;m} \\ &\quad - \left[(\gamma^{mk} \delta_i^p + \gamma^{mp} \delta_i^k) \gamma^{ql} \hat{S}_{qp} \frac{p_l p_k}{np(m - np)} \delta \right]_{;m} \end{aligned}$$

- Redefine momentum, such that $P_i = \int d^3\mathbf{x} \mathcal{H}_i^{\text{matter}}$:

$$\mathcal{H}_i^{\text{matter}} = P_i \delta + [\dots]_{,m}$$

$$P_i \equiv p_i - \frac{1}{2} \left[\gamma^{lj} \gamma^{kp} \gamma_{il,p} - \frac{p_m p_q}{np(m - np)} \gamma^{mj} \gamma^{kl} \gamma^{qp} \gamma_{lp,i} \right] \hat{S}_{jk}$$



Redefinition of Spin

- In Minkowski space, we have:

$$\hat{S}_{ij}\hat{S}_{ij} = \text{const.}$$

- Covariant generalisation:

$$\gamma^{ik}\gamma^{jl}\hat{S}_{ij}\hat{S}_{kl} = \text{const.}$$

- Need symmetric root of γ_{ij} (dreibein), cf. Kibble (1963):

$$e_{il}e_{lj} = \gamma_{ij}, \quad e_{ij} = e_{ji}$$

- Constant-euclidean-length spin $S_{(i)(j)} = \epsilon_{ijk}S_{(k)}$:

$$\hat{S}_{kl} = e_{ki}e_{lj}S_{(i)(j)}, \quad S_{(i)(j)}S_{(i)(j)} = \text{const.}$$



The Final Result for our Formalism

$$\mathcal{H}^{\text{matter}} = -nP\delta - \frac{1}{2}t_{ij}^k \gamma^{ij},{}_{,k} - \left[\frac{P_l}{m - nP} \gamma^{ij} \gamma^{kl} \hat{S}_{jk} \delta \right],{}_i$$

$$\begin{aligned} \mathcal{H}_i^{\text{matter}} &= P_i \delta + \frac{1}{2} \left[\gamma^{mk} \hat{S}_{ik} \delta \right],{}_m \\ &\quad - \left[\frac{P_l P_k}{nP(m - nP)} (\gamma^{mk} \delta_i^p + \gamma^{mp} \delta_i^k) \gamma^{ql} \hat{S}_{qp} \delta \right],{}_m \end{aligned}$$

$$\sqrt{\gamma} \hat{T}_{ij} = -\frac{P_i P_j}{nP} \delta + t_{ij,k}^k + \mathcal{O}(G)$$

$$t_{ij}^k \equiv \gamma^{kl} \frac{\hat{S}_{l(i} P_{j)}}{nP} \delta + \gamma^{kl} \gamma^{mn} \frac{\hat{S}_{m(i} P_{j)} P_n P_l}{(nP)^2 (m - nP)} \delta$$



Correct evolution equations?

$$H^{\text{matter}} = \int d^3\mathbf{x} (N\mathcal{H}^{\text{matter}} - N^i \mathcal{H}_i^{\text{matter}})$$

- Inspection of our matter expressions:

$$\mathcal{H}^{\text{matter}} = -nP\delta - \frac{1}{2} t_{ij}^k \gamma^{ij},{}_{,k} - \left[\frac{P_l}{m - nP} \gamma^{ij} \gamma^{kl} \hat{S}_{jk} \delta \right],{}_i$$

$$\sqrt{\gamma} \hat{T}_{ij} = -\frac{P_i P_j}{nP} \delta + t_{ij,k}^k + \mathcal{O}(G)$$

- We have at least:

$$\frac{\delta H^{\text{matter}}}{\delta \gamma^{ij}} = \frac{1}{2} N \sqrt{\gamma} \hat{T}_{ij} + \mathcal{O}(G)$$

- **Sufficient** for 2PN $\hat{=}$ NLO!



Global Poincaré Invariance: Preliminary Results

$$\mathcal{H}_i^{\text{matter}} = P_i \delta + \frac{1}{2} \left[\gamma^{mk} \hat{S}_{ik} \delta \right] - \left[\frac{P_l P_k}{nP(m-nP)} (\gamma^{mk} \delta_i^p + \gamma^{mp} \delta_i^k) \gamma^{ql} \hat{S}_{qp} \delta \right]_{,m}$$

- By construction, we have: $P_i = \int d^3\mathbf{x} \mathcal{H}_i^{\text{matter}}$
- We also have:

$$J_{ij} = \int d^3\mathbf{x} (x^i \mathcal{H}_j^{\text{matter}} - x^j \mathcal{H}_i^{\text{matter}}) = \hat{z}^i P_j - \hat{z}^j P_i + S_{(i)(j)}$$

- Implies that a **major part** of the Poincaré algebra is fulfilled!
- Justifies the use of standard Poisson-brackets for matter in the ADMTT gauge:

$$\{\hat{z}^i(t), P_j(t)\} = \delta_{ij}, \quad \{S_{(i)}(t), S_{(j)}(t)\} = \epsilon_{ijk} S_{(k)}(t)$$



Result with 4-dim. Covariant Stress-Energy Tensor

- Generalisation of Newton-Wigner SSC:

$$\delta x^\mu = -\frac{S^{\mu\nu} n_\nu}{m - np}$$

$$S^{\mu\nu} = \hat{S}^{\mu\nu} + p^\mu n_\lambda \hat{S}^{\nu\lambda} / m - p^\nu n_\lambda \hat{S}^{\mu\lambda} / m$$

- We need an additional term in P_i : $P_i = p_i - n_\mu S^{k\mu} K_{ik} + \dots$
- We add a Lie-shift:

$$\begin{aligned} \sqrt{\gamma} T^{\mu\nu} n_\mu n_\nu + \mathcal{L}_{m\delta x^\sigma} [\sqrt{\gamma} T^{\mu\nu} n_\mu n_\nu] &= \mathcal{H}^{\text{matter}} \\ -\sqrt{\gamma} T_i^\nu n_\nu + \mathcal{L}_{m\delta x^\sigma} [-\sqrt{\gamma} T_i^\nu n_\nu] &= \\ \mathcal{H}_i^{\text{matter}} - \delta x^j (P_{i;j} + P_{j;i} - P_{ij}) \delta & \end{aligned}$$

- P_i must be parallel shifted along δx^j without rotation.
- **Agreement** with our previous result!



Action Principle

$$W = \int dt \left(\sum_a P_{ai} \dot{\hat{z}}_a^i + \sum_a S_a^{(i)} \Omega_a^{(i)} + \frac{1}{16\pi} \int d^3x \pi_{\text{TT}}^{ij} \dot{h}_{ij}^{\text{TT}} - H_{\text{ADM}} \left[\hat{z}_a^i, P_{ai}, S_a^{(j)}, h_{ij}^{\text{TT}}, \pi_{\text{TT}}^{ij} \right] \right)$$

- Formulas: $\Omega_a^{(i)} = \frac{1}{2} \epsilon_{ijk} \Lambda_{a(l)(j)} \dot{\Lambda}_{a(l)(k)}$,
 $\Lambda_{a(i)(k)} \Lambda_{a(j)(k)} = \Lambda_{a(k)(i)} \Lambda_{a(k)(j)} = \delta_{ij}$.
- Variables to vary: P_{ai} , \hat{z}_a^i , $S_a^{(i)}$, $\Lambda_{a(i)(j)}$.
- Equations of motion for matter:

$$\dot{\hat{z}}_a^i(t) = \frac{\delta \int dt' H_{\text{ADM}}}{\delta P_{ai}(t)}, \quad \dot{P}_{ai}(t) = - \frac{\delta \int dt' H_{\text{ADM}}}{\delta \hat{z}_a^i(t)}$$

$$\Omega_a^{(i)}(t) = \frac{\delta \int dt' H_{\text{ADM}}}{\delta S_a^{(i)}(t)}, \quad \dot{S}_a^{(i)}(t) = \epsilon_{ijk} \Omega_a^{(j)}(t) S_a^{(k)}(t)$$



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The Constraint Algebra I

$$\{\mathcal{H}(x), \mathcal{H}(x')\} = - \left[\mathcal{H}_i(x) \gamma^{ij}(x) + \mathcal{H}_i(x') \gamma^{ij}(x') \right] \delta_{\mathbf{x}\mathbf{x}',j}$$

$$\{\mathcal{H}_i(x), \mathcal{H}(x')\} = - \mathcal{H}(x) \delta_{\mathbf{x}\mathbf{x}',i}$$

$$\{\mathcal{H}_i(x), \mathcal{H}_j(x')\} = - \mathcal{H}_j(x) \delta_{\mathbf{x}\mathbf{x}',i} - \mathcal{H}_i(x') \delta_{\mathbf{x}\mathbf{x}',j}$$

- This algebra is valid for point-masses.
- The coupling to gravity must be simple:
 - $\mathcal{H}^{\text{matter}}$ does not depend on derivatives of γ_{ij} .
 - $\mathcal{H}_i^{\text{matter}}$ does not depend on γ_{ij} at all.
- Spinning objects do not couple that simple.
- An algebra of (first-class) constraints is related to gauge symmetries.
- Algebra quite robust even if matter is coupled to gravity.
- Extension of this algebra is possible, if gauge structure is extended.



The Constraint Algebra II

- Consistent first-class constraint algebra necessary for gauge independent formulation.
- Mixed matter-field contribution for simple coupling:

$$\{\mathcal{H}_i^{\text{field}}(x), \mathcal{H}^{\text{matter}}(x')\} = \sqrt{\gamma} T_{jk}(x') [\delta_i^j \gamma^{kl}(x') \delta_{xx',l} + \gamma^{jk}_{,i}(x') \delta_{xx'}]$$

- Matter-only algebra for simple coupling:

$$\{\mathcal{H}^m(x), \mathcal{H}^m(x')\} = - [\mathcal{H}_i^m(x) \gamma^{ij}(x) + \mathcal{H}_i^m(x') \gamma^{ij}(x')] \delta_{xx',j}$$

$$\{\mathcal{H}_i^m(x), \mathcal{H}^m(x')\} = -\mathcal{H}^m(x) \delta_{xx',i} - \sqrt{\gamma} T_{jk}(x') [\delta_i^j \gamma^{kl}(x') \delta_{xx',l} + \gamma^{jk}_{,i}(x') \delta_{xx'}]$$

$$\{\mathcal{H}_i^m(x), \mathcal{H}_j^m(x')\} = -\mathcal{H}_i^m(x) \delta_{xx',j} - \mathcal{H}_j^m(x') \delta_{xx',i}$$

- Minkowski-limit of this algebra can be considered ...



Algebra of Spinning Objects Stress-Energy-Tensor Components in Minkowski Space

$$\{\mathcal{H}^m(x), \mathcal{H}^m(x')\} = -[\mathcal{H}_i^m(x) + \mathcal{H}_i^m(x')] \delta_{xx',i}$$

$$\{\mathcal{H}_i^m(x), \mathcal{H}^m(x')\} = -\mathcal{H}^m(x) \delta_{xx',i} - T_{ij}(x') \delta_{xx',j}$$

$$\{\mathcal{H}_i^m(x), \mathcal{H}_j^m(x')\} = -\mathcal{H}_j^m(x) \delta_{xx',i} - \mathcal{H}_i^m(x') \delta_{xx',j} + \partial_n \partial'_q [h_{inj}(x) \delta_{xx'}]$$

$$h_{inj}(x) = \left[-\hat{S}_{q)(n\mathcal{P}_i)j} - \delta^{kl} \frac{p_k \hat{S}_{l(n\mathcal{P}_i)(j p_q)}}{(np)(m-np)} + \delta^{kl} \frac{p_k \hat{S}_{l(q\mathcal{P}_j)(i p_n)}}{(np)(m-np)} \right] \delta$$

$$\mathcal{P}_{ij} \equiv \delta_{ij} - \frac{p_i p_j}{(np)^2}$$

- This is a part of the Stress-Energy-Tensor algebra, $\mathcal{H}^m(x) = T^{00}$ and $\mathcal{H}_i^m(x) = T^{0i}$.
- Occurance of $h_{inj}(x)$ shows already in the Minkowsky case that coupling to gravity can not be simple.
- Dirac field also has $h_{inj}(x) \neq 0$.



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Perturbative Solution of Partial Differential Equations

Example:

- $\Delta f(\mathbf{x}) = a(\mathbf{x}) + b(\mathbf{x})f(\mathbf{x}) + c(\mathbf{x})[f(\mathbf{x})]^2 + \dots$
- In general: vectors, other diff. op., derivatives on RHS, ...
- Perturbative expansion, e.g. $a = a_{(1)} + a_{(2)} + a_{(3)} + \dots$
- Leads to recursive equations:

$$\Delta f_{(1)}(\mathbf{x}) = a_{(1)}(\mathbf{x})$$

$$\Delta f_{(2)}(\mathbf{x}) = a_{(2)}(\mathbf{x}) + b_{(1)}(\mathbf{x})f_{(1)}(\mathbf{x})$$

$$\Delta f_{(3)}(\mathbf{x}) = a_{(3)}(\mathbf{x}) + b_{(1)}(\mathbf{x})f_{(2)}(\mathbf{x}) + b_{(2)}(\mathbf{x})f_{(1)}(\mathbf{x}) \\ + c_{(1)}(\mathbf{x})[f_{(1)}(\mathbf{x})]^2$$

⋮

- Delta sources \Rightarrow **Regularisation**



Calculation of Hamiltonians

- Going over to ADMTT gauge:

$$\gamma_{ij} = \left(1 + \frac{1}{8}\phi\right)^4 \delta_{ij} + h_{ij}^{\text{TT}}$$

$$\pi^{ij} = \tilde{\pi}^{ij} + \pi_{\text{TT}}^{ij}$$

- Expansion of the constraints in c^{-2} .
- Solve constraints for ϕ and $\tilde{\pi}^{ij}$.
- Calculate Hamiltonian:

$$H_{\text{ADM}}[X_a^i, P_{ai}, S_{a(i)}, h_{ij}^{\text{TT}}, \pi_{\text{TT}}^{kl}] = -\frac{1}{16\pi} \int d^3\mathbf{x} \Delta\phi$$

- Near-zone expansion of wave equation $\square h_{ij}^{\text{TT}} = \dots$
- Elimination of h_{ij}^{TT} and π_{TT}^{kl} .



The Leading-Order (LO) in Spin

- LO Spin-Orbit Hamiltonian:

$$H_{\text{SO}}^{\text{LO}} = \sum_a \sum_{b \neq a} \frac{1}{r_{ab}^2} (\mathbf{S}_a \times \mathbf{n}_{ab}) \cdot \left[\frac{3m_b}{2m_a} \mathbf{P}_a - 2\mathbf{P}_b \right]$$

- LO Spin₁-Spin₂ Hamiltonian:

$$H_{\text{SS}}^{\text{LO}} = \sum_a \sum_{b \neq a} \frac{1}{2r_{ab}^3} [3(\mathbf{S}_a \cdot \mathbf{n}_{ab})(\mathbf{S}_b \cdot \mathbf{n}_{ab}) - (\mathbf{S}_a \cdot \mathbf{S}_b)]$$

- Center of mass vector:

$$\mathbf{G}_{\text{SO}}^{\text{LO}} = \sum_a \frac{1}{2m_a} (\mathbf{P}_a \times \mathbf{S}_a), \quad \mathbf{G}_{\text{SS}}^{\text{LO}} = 0$$



NLO Spin-Orbit Hamiltonian (DJS 2007)

$$\begin{aligned}
 H_{\text{SO}}^{\text{NLO}} = & -\frac{((\mathbf{P}_1 \times \mathbf{S}_1) \cdot \mathbf{n}_{12})}{r_{12}^2} \left[\frac{5m_2 \mathbf{P}_1^2}{8m_1^3} + \frac{3(\mathbf{P}_1 \cdot \mathbf{P}_2)}{4m_1^2} - \frac{3\mathbf{P}_2^2}{4m_1 m_2} \right. \\
 & \left. + \frac{3(\mathbf{P}_1 \cdot \mathbf{n}_{12})(\mathbf{P}_2 \cdot \mathbf{n}_{12})}{4m_1^2} + \frac{3(\mathbf{P}_2 \cdot \mathbf{n}_{12})^2}{2m_1 m_2} \right] \\
 & + \frac{((\mathbf{P}_2 \times \mathbf{S}_1) \cdot \mathbf{n}_{12})}{r_{12}^2} \left[\frac{(\mathbf{P}_1 \cdot \mathbf{P}_2)}{m_1 m_2} + \frac{3(\mathbf{P}_1 \cdot \mathbf{n}_{12})(\mathbf{P}_2 \cdot \mathbf{n}_{12})}{m_1 m_2} \right] \\
 & + \frac{((\mathbf{P}_1 \times \mathbf{S}_1) \cdot \mathbf{P}_2)}{r_{12}^2} \left[\frac{2(\mathbf{P}_2 \cdot \mathbf{n}_{12})}{m_1 m_2} - \frac{3(\mathbf{P}_1 \cdot \mathbf{n}_{12})}{4m_1^2} \right] \\
 & - \frac{((\mathbf{P}_1 \times \mathbf{S}_1) \cdot \mathbf{n}_{12})}{r_{12}^3} \left[\frac{11m_2}{2} + \frac{5m_2^2}{m_1} \right] \\
 & + \frac{((\mathbf{P}_2 \times \mathbf{S}_1) \cdot \mathbf{n}_{12})}{r_{ab}^3} \left[6m_1 + \frac{15m_2}{2} \right] + (1 \leftrightarrow 2)
 \end{aligned}$$



NLO Spin₁-Spin₂ Hamiltonian I

$$\begin{aligned}
 H_{SS}^{\text{NLO}} = & \frac{1}{2m_1 m_2 r_{12}^3} \left[\frac{3}{2} ((\mathbf{P}_1 \times \mathbf{S}_1) \cdot \mathbf{n}_{12}) ((\mathbf{P}_2 \times \mathbf{S}_2) \cdot \mathbf{n}_{12}) \right. \\
 & + 6 ((\mathbf{P}_2 \times \mathbf{S}_1) \cdot \mathbf{n}_{12}) ((\mathbf{P}_1 \times \mathbf{S}_2) \cdot \mathbf{n}_{12}) \\
 & - 15 (\mathbf{S}_1 \cdot \mathbf{n}_{12}) (\mathbf{S}_2 \cdot \mathbf{n}_{12}) (\mathbf{P}_1 \cdot \mathbf{n}_{12}) (\mathbf{P}_2 \cdot \mathbf{n}_{12}) \\
 & - 3 (\mathbf{S}_1 \cdot \mathbf{n}_{12}) (\mathbf{S}_2 \cdot \mathbf{n}_{12}) (\mathbf{P}_1 \cdot \mathbf{P}_2) \\
 & + 3 (\mathbf{S}_1 \cdot \mathbf{P}_2) (\mathbf{S}_2 \cdot \mathbf{n}_{12}) (\mathbf{P}_1 \cdot \mathbf{n}_{12}) \\
 & + 3 (\mathbf{S}_2 \cdot \mathbf{P}_1) (\mathbf{S}_1 \cdot \mathbf{n}_{12}) (\mathbf{P}_2 \cdot \mathbf{n}_{12}) \\
 & + 3 (\mathbf{S}_1 \cdot \mathbf{P}_1) (\mathbf{S}_2 \cdot \mathbf{n}_{12}) (\mathbf{P}_2 \cdot \mathbf{n}_{12}) \\
 & + 3 (\mathbf{S}_2 \cdot \mathbf{P}_2) (\mathbf{S}_1 \cdot \mathbf{n}_{12}) (\mathbf{P}_1 \cdot \mathbf{n}_{12}) \\
 & - 3 (\mathbf{S}_1 \cdot \mathbf{S}_2) (\mathbf{P}_1 \cdot \mathbf{n}_{12}) (\mathbf{P}_2 \cdot \mathbf{n}_{12}) + (\mathbf{S}_1 \cdot \mathbf{P}_1) (\mathbf{S}_2 \cdot \mathbf{P}_2) \\
 & \left. - \frac{1}{2} (\mathbf{S}_1 \cdot \mathbf{P}_2) (\mathbf{S}_2 \cdot \mathbf{P}_1) + \frac{1}{2} (\mathbf{S}_1 \cdot \mathbf{S}_2) (\mathbf{P}_1 \cdot \mathbf{P}_2) \right]
 \end{aligned}$$



NLO Spin₁-Spin₂ Hamiltonian II

$$\begin{aligned}
 & + \frac{3}{2m_1^2 r_{12}^3} [-((\mathbf{P}_1 \times \mathbf{S}_1) \cdot \mathbf{n}_{12})(\mathbf{P}_1 \times \mathbf{S}_2) \cdot \mathbf{n}_{12} \\
 & \quad + (\mathbf{S}_1 \cdot \mathbf{S}_2)(\mathbf{P}_1 \cdot \mathbf{n}_{12})^2 - (\mathbf{S}_1 \cdot \mathbf{n}_{12})(\mathbf{S}_2 \cdot \mathbf{P}_1)(\mathbf{P}_1 \cdot \mathbf{n}_{12})] \\
 & + \frac{3}{2m_2^2 r_{12}^3} [-((\mathbf{P}_2 \times \mathbf{S}_2) \cdot \mathbf{n}_{12})(\mathbf{P}_2 \times \mathbf{S}_1) \cdot \mathbf{n}_{12} \\
 & \quad + (\mathbf{S}_1 \cdot \mathbf{S}_2)(\mathbf{P}_2 \cdot \mathbf{n}_{12})^2 - (\mathbf{S}_2 \cdot \mathbf{n}_{12})(\mathbf{S}_1 \cdot \mathbf{P}_2)(\mathbf{P}_2 \cdot \mathbf{n}_{12})] \\
 & + \frac{6(m_1 + m_2)}{r_{12}^4} [(\mathbf{S}_1 \cdot \mathbf{S}_2) - 2(\mathbf{S}_1 \cdot \mathbf{n}_{12})(\mathbf{S}_2 \cdot \mathbf{n}_{12})]
 \end{aligned}$$



NLO Center of Mass

$$\begin{aligned}
 \mathbf{G}_{\text{SO}}^{\text{NLO}} = & - \sum_a \frac{\mathbf{P}_a^2}{8m_a^3} (\mathbf{P}_a \times \mathbf{S}_a) \\
 & + \sum_a \sum_{b \neq a} \frac{m_b}{4m_a r_{ab}} \left[((\mathbf{P}_a \times \mathbf{S}_a) \cdot \mathbf{n}_{ab}) \frac{5\mathbf{x}_a + \mathbf{x}_b}{r_{ab}} - 5(\mathbf{P}_a \times \mathbf{S}_a) \right] \\
 & + \sum_a \sum_{b \neq a} \frac{1}{r_{ab}} \left[\frac{3}{2} (\mathbf{P}_b \times \mathbf{S}_a) - \frac{1}{2} (\mathbf{n}_{ab} \times \mathbf{S}_a) (\mathbf{P}_b \cdot \mathbf{n}_{ab}) \right. \\
 & \quad \left. - ((\mathbf{P}_a \times \mathbf{S}_a) \cdot \mathbf{n}_{ab}) \frac{\mathbf{x}_a + \mathbf{x}_b}{r_{ab}} \right]
 \end{aligned}$$

$$\mathbf{G}_{\text{SS}}^{\text{NLO}} = \frac{1}{2} \sum_a \sum_{b \neq a} \left\{ [3(\mathbf{S}_a \cdot \mathbf{n}_{ab})(\mathbf{S}_b \cdot \mathbf{n}_{ab}) - (\mathbf{S}_a \cdot \mathbf{S}_b)] \frac{\mathbf{x}_a}{r_{ab}^3} + (\mathbf{S}_b \cdot \mathbf{n}_{ab}) \frac{\mathbf{S}_a}{r_{ab}^2} \right\}$$



Global Poincaré Invariance

- Check of Poincaré algebra is important:
 - Generally a good indicator for errors.
 - **Validates Poisson-brackets for our variables.**
- Generators of the Poincaré group:

$$\mathbf{P} = \sum_a \mathbf{P}_a$$

$$\mathbf{J} = \sum_a \mathbf{x}_a \times \mathbf{P}_a + \sum_a \mathbf{S}_a$$


$$\mathbf{G} = \mathbf{G}_{\text{PM}} + \mathbf{G}_{\text{SO}}^{\text{LO}} + \mathbf{G}_{\text{SS}}^{\text{LO}} + \mathbf{G}_{\text{SO}}^{\text{NLO}} + \mathbf{G}_{\text{SS}}^{\text{NLO}}$$


$$H_{\text{ADM}} = H_{\text{PM}} + H_{\text{SO}}^{\text{LO}} + H_{\text{SS}}^{\text{LO}} + H_{\text{SO}}^{\text{NLO}} + H_{\text{SS}}^{\text{NLO}}$$


- Point-mass (PM) contributions must be included.
- **Poincaré algebra is fulfilled!**



NLO Spin Hamiltonians in the Literature

-  T. Damour, P. Jaranowski, and G. Schäfer
Hamiltonian of two spinning compact bodies with next-to-leading order gravitational spin-orbit coupling
Phys. Rev. D submitted, arXiv:0711.1048v1 [gr-qc]

-  S. Hergt and G. Schäfer
Source terms for Kerr geometry in approximate ADM coordinates and higher-order-in-spin interaction Hamiltonians for binary black holes
Phys. Rev. D submitted, arXiv:0712.1515v1 [gr-qc]

-  J. Steinhoff, S. Hergt, and G. Schäfer
On the next-to-leading order gravitational spin(1)-spin(2) dynamics
Phys. Rev. D (R) submitted, arXiv:0712.1716v1 [gr-qc]



Outline

- 1 Introduction
 - Spinning objects in SR and GR
 - The ADM formalism
- 2 Our Formulation
 - Strategy of our approach
 - Details on the derivation
 - Gauge independent formalism?
- 3 Application
 - Hamiltonians
 - Comparison with other Methods



SO Hamiltonian of Damour, Jaranowski, and Schäfer

arXiv:0711.1048v1 [gr-qc], submitted to Phys. Rev. D

- Hamiltonian is linear in a constant-euclidean-length \mathbf{S}_a :

$$H_{\text{SO}}^{\text{NLO}}(\mathbf{x}_a, \mathbf{p}_a, \mathbf{S}_a) = \sum_{a=1,2} \boldsymbol{\Omega}_a(\mathbf{x}_a, \mathbf{p}_a) \cdot \mathbf{S}_a$$

- EOM from Hamiltonian: $\dot{\mathbf{S}}_a = \boldsymbol{\Omega}_a \times \mathbf{S}_a$
- EOM in covariant SSC: $\frac{DS^{\mu\nu}}{d\tau} = 0$
- Compare both EOM using $\mathbf{S}_a^2 = \text{const.}$ (not unique).
- Resulting formula for $\boldsymbol{\Omega}_a$ depends on metric at \mathbf{x}_a .
- **Metric of point-masses suffices for $\boldsymbol{\Omega}_a$!**
- **Identical** to our result.



Spin₁-Spin₂ Hamiltonian via modified DJS Method

- Ansatz for the Hamiltonian:

$$\begin{aligned} H_{SS}^{\text{NLO}}(\mathbf{x}_a, \mathbf{p}_a, \mathbf{S}_a) &= \tilde{\Omega}_{ij}(\mathbf{x}_a, \mathbf{p}_a) S_1^{(i)} S_2^{(j)} \\ &= \boldsymbol{\Omega}_1(\mathbf{x}_a, \mathbf{p}_a, \mathbf{S}_2) \cdot \mathbf{S}_1 \end{aligned}$$

- DJS formula can be used for $\Omega_1^i \equiv \tilde{\Omega}_{ij} S_2^{(j)}$.
- Now \mathbf{S}_2 -dependent part of the metric is needed.
- Metric is calculated with our source.
- Again **identical** to our result.
- Lapse and shift were used.
- EOM were used.



Spin₁-Spin₂ Potential of Porto and Rothstein

- First (incomplete) result:



R. A. Porto and I. Z. Rothstein

Calculation of the First Nonlinear Contribution to the General-Relativistic Spin-Spin Interaction for Binary Systems

Phys. Rev. Lett. **97**, 021101 (2006)

- Prompt **confirmation** of our spin₁-spin₂ Hamiltonian in arXiv:0712.1716v1:



R. A. Porto and I. Z. Rothstein

Comment on 'On the next-to-leading order gravitational spin(1)-spin(2) dynamics' by J. Steinhoff et al

arXiv:0712.2032v1 [gr-qc]

- Their new, complete potential relates to our Hamiltonian via Legendre and canonical transformation.



Summary

- Our formalism describes the correct NLO spin dynamics.
- Application is formally possible up to any desired order.

- Outlook
 - Further application of our formalism.
 - Gauge independent formulation?
 - Up to which order is our formalism correct?

